# Structured Graph Learning via Laplacian Spectral Constraints

Graphical modeling  $\mathcal{G} = (\mathcal{V}, \mathcal{E}, \mathbf{W})$ 



#### Representing knowledge through graphical model

- A graph is an intuitive way of **representing** and **visualizing** the relationships between entities.
- Nodes:  $\mathcal{V} = \{1, 2, \dots, p\}$  correspond to the **entities**.
- Edges:  $\mathcal{E} = \{(1,2), (1,3), \dots, (3,p), \dots\}$  encode the relation**ships** between entities.
- Elements of the weight matrix W encode the **strength** of the relationships.

#### Graph learning from data

Let  $Y \in \mathbb{R}^{n \times p} = [\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_p]$  be data matrix, each column  $\mathbf{y}_i \in \mathbb{R}^n$  resides on one of p nodes of a graph  $\mathcal{G}$ , while each of the n rows of Y is an observation corresponding to one of the nodes of the graph.



#### Gaussian graphical modeling (GGM)

Sample covariance matrix  $S = \frac{1}{n}Y^{\top}Y$ .

maximize  $\log \det(\Theta) - \operatorname{tr}(S\Theta) - \alpha h(\Theta)$ ,  $\Theta \in \mathcal{S}^p_+$ 

- When the data follows a Gaussian distribution  $\mathbf{x} \sim \mathcal{N}(0, \Theta^{-1})$ , it is the penalized **MLE** of the **precision matrix**.
- The entries of  $\Theta$  determines a **conditional** graph  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$  :

$$\begin{aligned} x_i \perp x_j | \mathbf{x}/(x_i, x_j) & \Longleftrightarrow \ \Theta = 0 \\ \Theta_{ij} \neq 0 & \Longleftrightarrow \ \{i, j\} \in \mathcal{E} \ \forall \ i \neq j. \end{aligned}$$

- $\mathbf{x} = [x_1, x_2, \dots, x_p]$  is a Gaussian Markov random field (GMRF).
- Also a  $\log \det(\cdot)$  regularized learning.
- If  $\Theta_{ij} \leq 0 \ \forall i \neq j$  then X is an **attractive** GMRF.

Limitations: Existing GGM based methods cannot learn a graph  $\Theta$  with specific structure [1, 2]. Enforcing structure is in general **NP-hard**.

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An R package for this paper is available at: https://cran.r-project.org/package=spectralGraphTopology. For more information visit: https://www.danielppalomar.com

### Structured graphs



Multi-component graph



# **Regular graph**

Grid graph



Modular graph



Bipartite graph

### **Graph Laplacian matrix**

• Laplacian matrix  $\Theta$  belongs to the following set:

$$\mathcal{S}_{\Theta} = \Big\{ \Theta | \Theta_{ij} = \Theta_{ji} \le 0 \text{ for } i \neq j, \Theta_{ii} = -\sum_{i \neq j} \Theta_{ij} \Big\}.$$

- **Smoothness**:  $tr(S\Theta)$  is used to quantify smoothness of signals: a smaller  $tr(S\Theta)$  indicating a smoother signal.
- The structural properties of many important graph structures can be inferred from eiegnvalues of the Laplacian matrix  $\boldsymbol{\lambda}(\Theta)$ .

$$\mathcal{S}_{\lambda} = \{ \boldsymbol{\lambda} \in \mathbb{R}^p | \{ \lambda_i = 0 \}_{i=1}^k, c_1 \leq \lambda_{k+1} \leq \cdots \leq \lambda_p \leq c_2 \}.$$



The number of zero eigenvalues denote the number of components in the graph.

## **Proposed formulation for structured graph** learning

maximize  $\log gdet(\Theta) - tr(S\Theta) - \alpha \|\Theta\|_{1,off}$ subject to  $\Theta \in \mathcal{S}_{\Theta}, \ \lambda(\Theta) \in \mathcal{S}_{\lambda}$ 

- Connected graph:  $S_{\lambda} = \{\lambda_1 = 0, c_1 \leq \lambda_2 \leq \cdots \leq \lambda_p \leq c_2\}$ with a proper choice of  $c_1 > 0, c_2 > 0$ .
- Grid, Modular, Erdos-Renyi and other connected structures can also be learned under the connected spectral constraint.

- $c_2$ }.

## Laplacian operator: $\mathcal{L}$

 $\mathcal{L}\mathbf{v}$ 

# **Problem reformulation**

Proposed algorithm

Sub-problem for  $\lambda$  :

A convex **isotonic** regression problem, we develop a **fast** iterative algorithm that converges within (p-k) iterations.

## **Algorithm summary**

- 3:

- 7: Return  $\mathbf{w}^{t+1}$
- lem.

• k-component graph:  $\mathcal{S}_{\lambda} = \{\{\lambda_i\}_{i=1}^k, c_1 \leq \lambda_{k+1} \leq \cdots \leq \lambda_p \leq n\}$ 

• *d*-regular graph:  $S_{\lambda} = \{\{\lambda_i = 0\}_{i=1}^k, c_1 \leq \lambda_{k+1} \leq \cdots \leq \lambda_p \leq \}$  $c_2$  and Diag $(\Theta) = d\mathbf{I}$ Cospectral graphs

 $\mathcal L$  maps a weight vector  $\mathbf w = [w_1, w_2, w_3, w_4, w_5, w_6]^ op$  to the Laplacian matrix.

	$\sum_{i=1,2,3} w_i$	$-w_1$	$-w_2$	$-w_3$	
$\mathbf{v} =$	$-w_1$	$\sum_{i=1,4,5} w_i$	$-w_4$	$-w_5$	
	$-w_2$	$-w_4$	$\sum_{i=2,4,6} w_i$	$-w_6$	•
	$-w_3$	$-w_5$	$-w_6$	$\sum_{i=3,5,6} w_i$	

 $\underset{\mathbf{w}, \boldsymbol{\lambda}, U}{\text{maximize}} \quad \log \text{gdet}(\text{Diag}(\boldsymbol{\lambda})) - \text{tr}(K\mathcal{L}\mathbf{w}) - \frac{\beta}{2} \|\mathcal{L}\mathbf{w} - U\text{Diag}(\boldsymbol{\lambda})U^{\top}\|_{F}^{2},$ subject to  $\mathbf{w} \geq 0, \ \boldsymbol{\lambda} \in \boldsymbol{S}_{\lambda}, \ U^{\top}U = I.$ 

where  $K = S + \alpha (I - \mathbf{11}^{+})$ .

Variables  $\mathcal{X} = (\mathbf{w}, \boldsymbol{\lambda}, U)$ : we develop a block majorizationminimization (**block-MM**) based algorithm. Sub-problem for  $\mathbf{w}$ :

 $\underset{\mathbf{w}>0}{\text{minimize}} \quad \frac{1}{2} \|\mathcal{L}\mathbf{w}\|_F^2 - \mathbf{c}^\top \mathbf{w}.$ 

where  $\mathbf{c} = \mathcal{L}^* \left( U \mathsf{Diag}(\boldsymbol{\lambda}) U^\top - \beta^{-1} K \right)$ . This is a constrained convex quadratic program, we solve it using the MM approach. Sub-problem for U:

maximize  $\operatorname{tr}\left(U^{\top}(\mathcal{L}\mathbf{w})U\mathsf{Diag}(\boldsymbol{\lambda})\right)$  subject to  $U^{\top}U = I$ .

 $\underset{\boldsymbol{\lambda} \in \mathcal{S}_{\lambda}}{\text{minimize}} \ -\log \text{gdet}(\text{Diag}(\boldsymbol{\lambda})) + \frac{\beta}{2} \| U^{\top}(\mathcal{L}\mathbf{w})\mathbf{U} - \text{Diag}(\boldsymbol{\lambda}) \|_{F}^{2}.$ 

1: **Input:** SCM S and  $S_{\lambda}$ .

2: while Stopping criteria not met do

 $\mathbf{w}^{t+1} = \left(\mathbf{w}^t - \frac{1}{2p}\left(\mathcal{L}^*(\mathcal{L}\mathbf{w}^t) - \mathbf{c}\right)\right)^{-1}$ 

 $U^{t+1} = eigenvectors(\mathcal{L}\mathbf{w}^{t+1})$ 

 $\lambda^{t+1}$ : Update via isotonic regression maxm iter (p-k). 6: end while

The **worst-case** computational complexity  $O(p^3)$ .

**Theorem**: The sequence  $(\mathbf{w}^t, U^t, \boldsymbol{\lambda}^t)$  generated by this algorithm converges to the set of KKT points of the optimization prob-





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